

Multimodal Generalist Agents: Reasoning, Reflecting, and Learning like Humans

Machine Learning Lab @ BIGAI



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Welcoming Diverse Approaches Keeps Machine Learning Strong

What technology counts as an "agent"? Instead of arguing, let's consider a spectrum along which various technologies are "agentic."

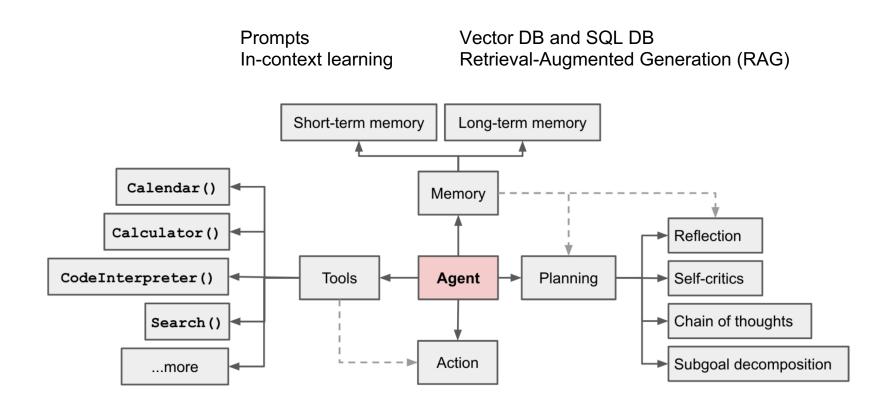


Letters	Technic	al Insights
🛱 Published		S Reading time
Jun 13, 2024		2 min read









https://lilianweng.github.io/posts/2023-06-23-agent/

Basic I: Tool-Use and Planning



Basic I: Tool-Use and Planning

Natural Language Visual Reasoning

LEFT:

RIGHT:

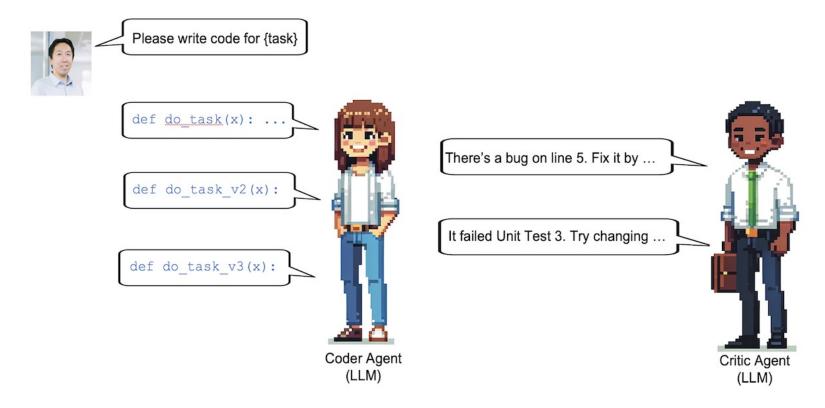




Statement: The left and right image contains a total of six people and two boats. Program:

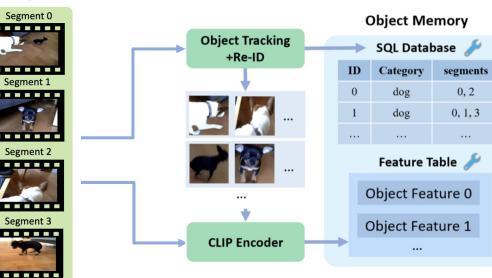
ANSWER0=Vqa(image=LEFT, question='How many people are in the image?')
ANSWER1=Vqa(image=RIGHT, question='How many people are in the image?')
ANSWER2=Vqa(image=LEFT, question='How many boats are in the image?')
ANSWER3=Vqa(image=RIGHT, question='How many boats are in the image?')
ANSWER4=Eval('{ANSWER0} + {ANSWER1} == 6 and {ANSWER2} + {ANSWER3} == 2')
RESULT=ANSWER4
Prediction: False

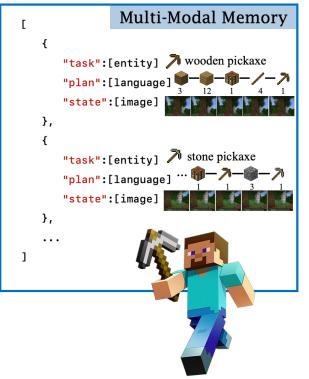
Basic II: Learning from Feedback



Basic III: Memory

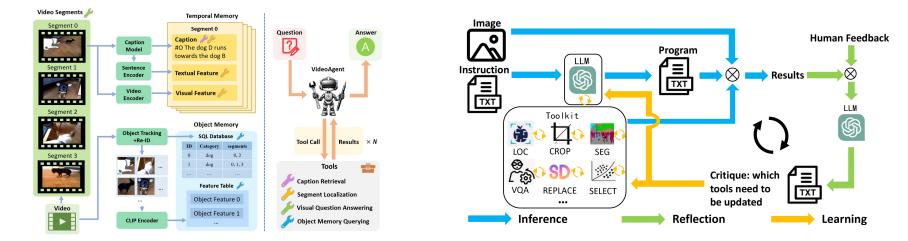
Video Segments





Video

1, 2, 3, Let's put them together...



VideoAgent Memory-augmented Multimodal Agent for Video Understanding

CLOVA + FIRE Reflecting and Learning from Feedback for Multimodal Agents



A Memory-augmented Multimodal Agent for Video Understanding



videoagent.github.io













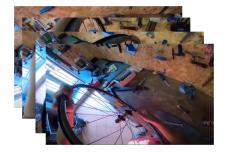
Mostly querying about **now**

- Short-term memory (~5-30s) 🔽
- Long-term memory (>30s) mostly X



Video understanding -- a secret sauce for embodied Al

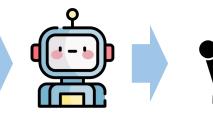








egocentric experiences (from long-form videos)





J



Pickup Object

Lift the bottle 30cm from the ground







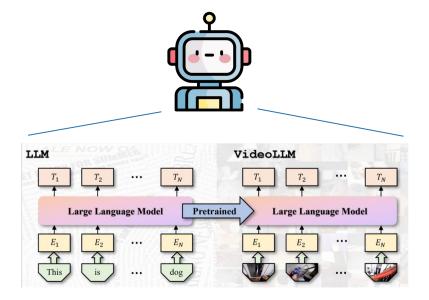
Video understanding -- a secret sauce for embodied Al



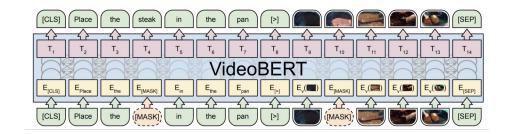




egocentric experiences (from long-form videos)



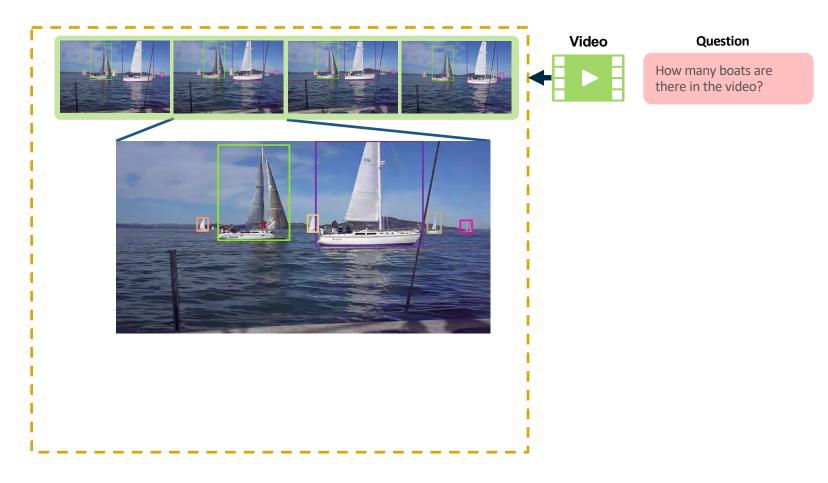




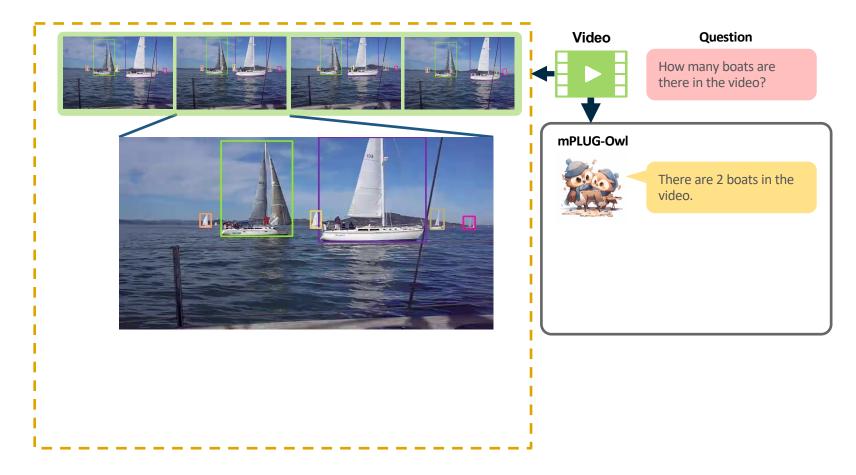


Video understanding -- a secret sauce for embodied AI

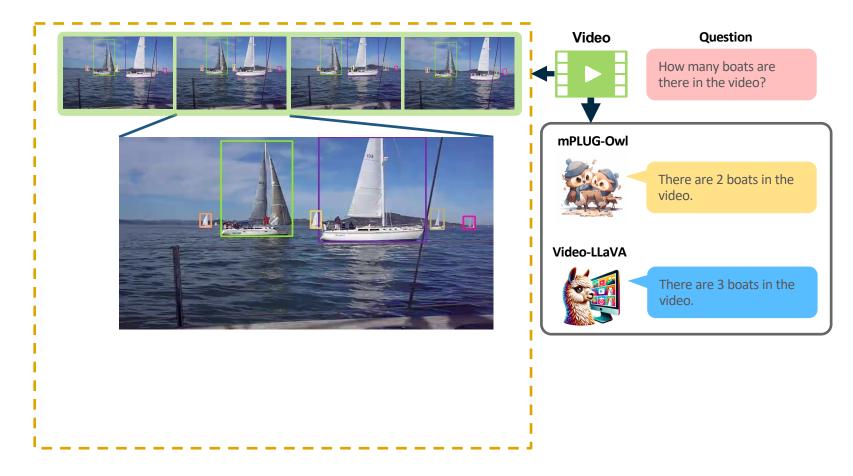




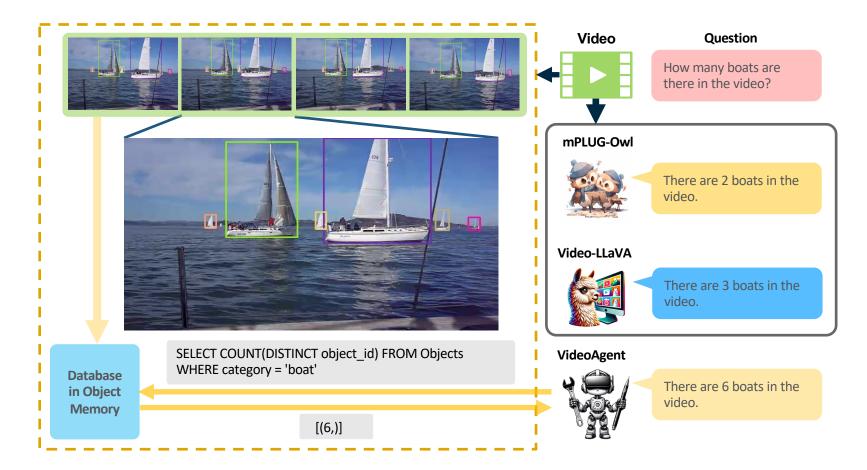
Machine Learning @ BIGAI



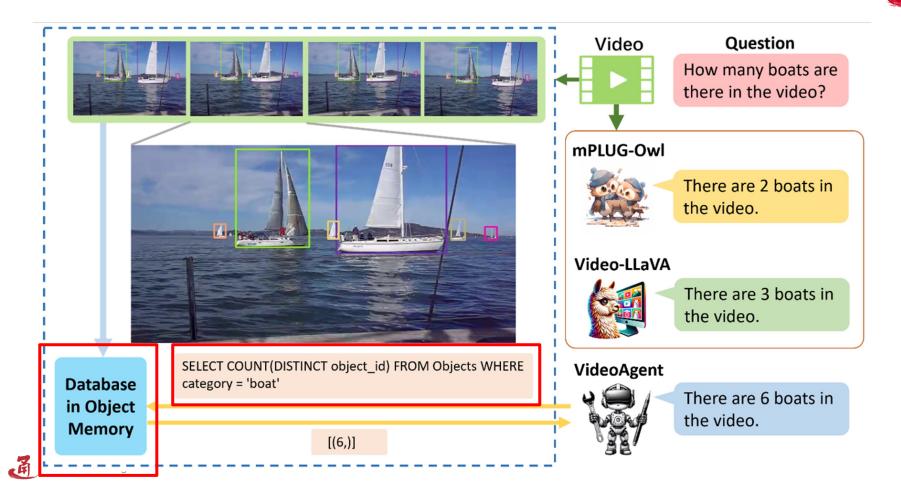
Machine Learning @ BIGAI



Machine Learning @ BIGAI



Video understanding -- a secret sauce for embodied Al



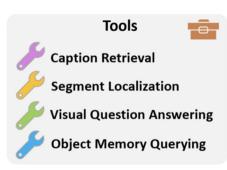
Introducing VideoAgent







unified memory





egocentric experience structured representations

Temporal Memory
ØDject Memory

tool-use LLM agent

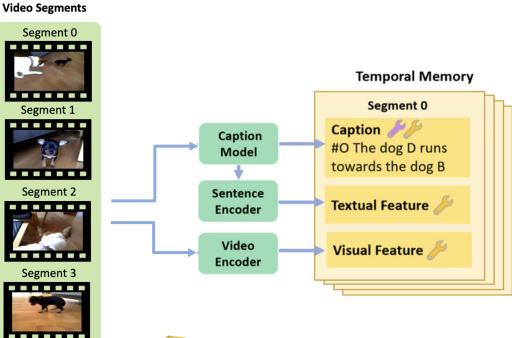


VideoAgent: unified memory

Video

unified memory

structured representations



Temporal Memory: segment-level (~2s) video content descriptions (text & vector)

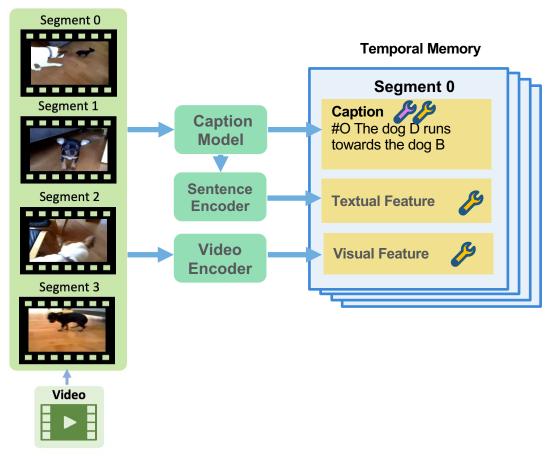
Temporal Memory

Caption Model: LaViLa

Sentence Encoder: text-embedding-3-large

Video Encoder: ViCLIP

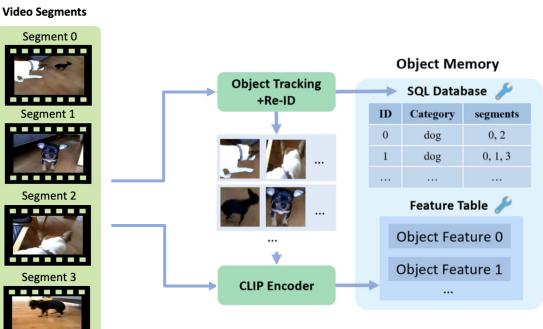
Video Segments



VideoAgent: unified memory

unified memory

structured representations





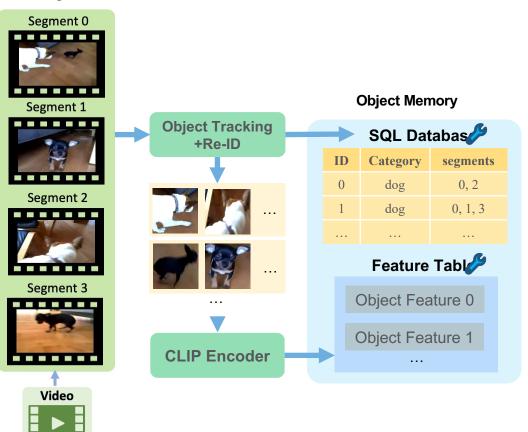
Object Memory: tracking the appearance of unique object instances as video streams (ID, category, CLIP feature)

Object Memory

Object Tracking: RT-DETR+ByteTrack

Object ReID: CLIP+DINOv2

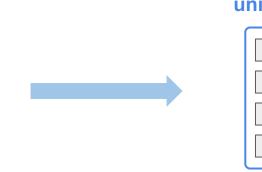
Video Segments

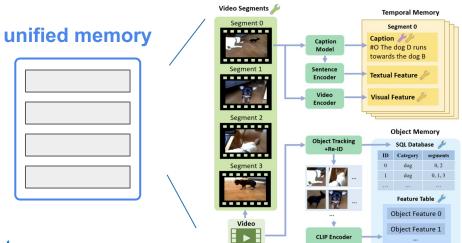




VideoAgent: unified memory



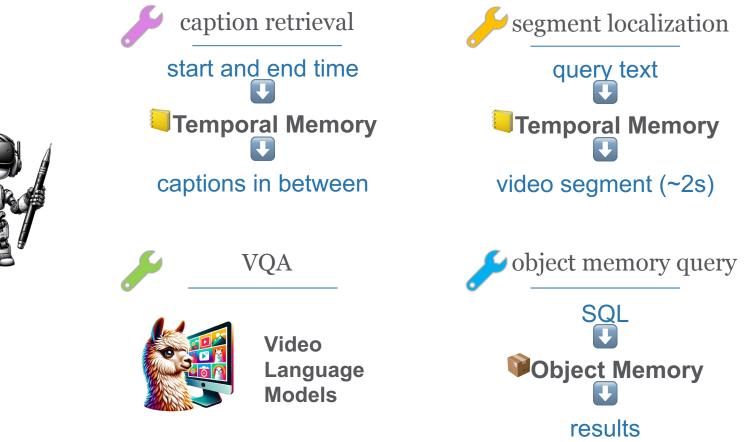




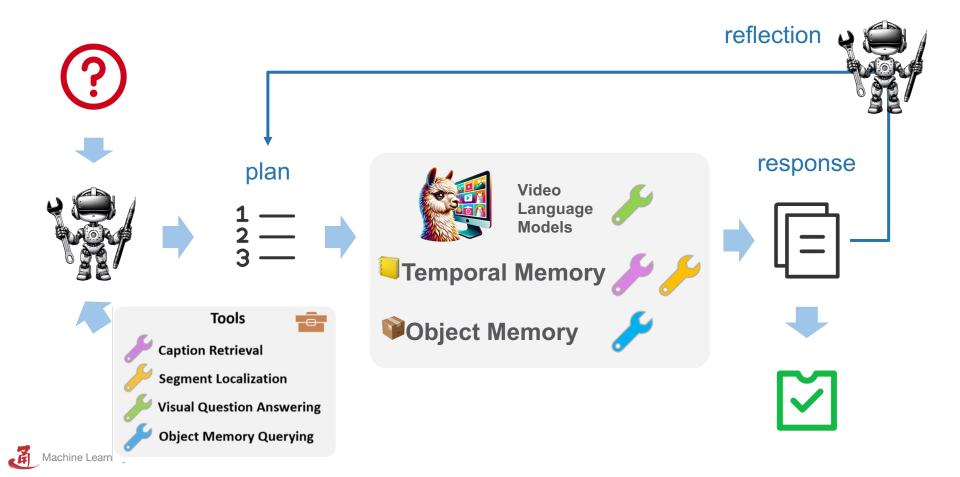
Real-time memory update:

- video segment captioning (**2Hz**)
- video segment embedding (**5Hz**)
- bject tracking & re-ID (15Hz)

VideoAgent: LLM tool-use



VideoAgent: LLM tool-use



What is the relationship between the boy and the adults?

Video











I need to find the segments where the boy and the adults are mentioned together. I will use the segment_localization tool to find these segments.

Action: segment_localization Action Input: "boy and adults"

Results: There are 28 segments in total, ranging from 0 to 27. The most relevant segments are: {13: '#O a child X interacts with the', 9: '#O A child X plays with a doll on the floor', ..., 24: '#C C dialogues with person'} The most relevant segments are 13 and 9 where a child is interacting or playing. I need to check these segments using the visual question answering tool

Action:

visual_question_answering Action Input: ("what is the relationship between the boy and the adults", 13)

Results: Description: The video is about a little boy who is pretending to cook in the kitchen. ... Answer: The video does not provide any information about the relationship between the boy and the adults. However, it can be inferred that the adults are supervising the boy as he plays with the toy kitchen set.

The description suggests that the boy is pretending to cook and the adults are likely supervising him. However, I need to check segment 9 to get more context.

Action:

visual_question_answering Action Input: ("what is the relationship between the boy and the adults", 9)

Results: Description: The video is about a man and a woman helping a little boy with a microwave oven. ... Answer: The boy is seen playing with the microwave while the adults are standing behind him. ...

The descriptions from both segments suggest that the adults are supervising the boy while he is playing. This suggests that the adults could be his parents or caregivers. **Final Answer:** The adults are likely the boy's parents or caregivers.

What is the relationship between the boy and the adults?

Video











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Temporal Memory

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Performances

EgoSchema (full set)							
FrozenBiLM VIOLET mPLUG-Owl InternVideo LLoVi Gemini 1.5 Pro							
26.9	19.9	30.2 32.0		50.3	63.2		
EgoSchema (subset, 500 questions)							
SeViLA	Video-LLaVA	ViperGPT	LLoVi	VideoAgent			
25.8	36.8	33.8	15.8	51.8	62.8		

Control with the second s

NExT-QA								
Method	Temporal Causal		Descriptive	Average				
Val. Set								
InternVideo	43.4	48.0	65.1	49.1				
SeViLA(zero-shot)	61.3	61.5	75.6	63.6				
TCR(pre-training)	-	-	-	66.1				
	Val. S	ubset (600)						
ViperGPT	17.2	19.0	26.7	21.0				
mPLUG-Owl	36.0	41.0	52.5	43.2				
Video-LLaVA	42.0	53.5	65.0	53.5				
SeViLA(zero-shot)	56.0	66.5	70.0	64.2				
VideoAgent	60.0	76.0	76.5	70.8				

~1min
 causal, temporal and action interactions

Ablation studies (on NExT-QA subset)

Type	VQA	Grounding	Captions	Database	Tem.	Cau.	Des.	Avg.
1	GPT-4V	\checkmark	\sim	w/ re-ID	64.0	78.0	82.0	74.7
6	×	×	\checkmark	×	34.0	46.0	42.0	40.7

With **Temporal Memory** and **caption retrieval** tool for only, VideoAgent attains **comparable** performances to state-of-the-art video language model mPLUG-Owl (43.2) already.

Ablation studies (on NExT-QA subset)

Type	VQA	Grounding	Captions	Database	Tem.	Cau.	Des.	Avg.
1	GPT-4V	\checkmark	\sim	w/ re-ID	64.0	78.0	82.0	74.7
4	×	×	\checkmark	w/ re-ID	48.0	52.0	68.0	56.0
5	×	×	\checkmark	w/o re-ID	46.0	46.0	54.0	48.7
6	×	×	\checkmark	×	34.0	46.0	42.0	40.7

Object Memory (SQL database) with **object memory query** tool boosts performances on all question categories.



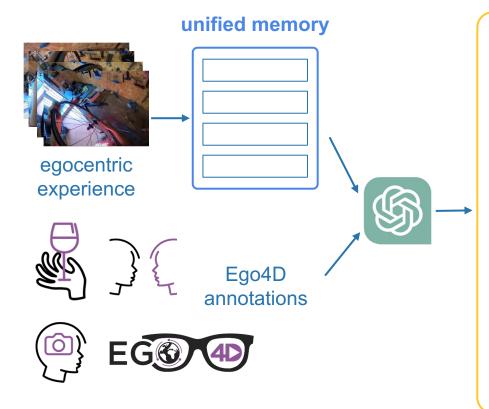
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2	Video-LLaVA	\checkmark	\checkmark	w/ re-ID	60.0	74.0	80.0	71.3
3	Video-LLaVA	\checkmark	\checkmark	×	46.0	64.0	78.0	62.7
	×			$\mathbf{w}/\mathbf{re-ID}$	48.0			
6	×	×	\checkmark	×	34.0	46.0	42.0	40.7

VQA tool and segment localization tool bring the most advantages to VideoAgent.

Data flywheel with VideoAgent

EgoSFT dataset



to t1 t2

Spatial Qs (about the present)

-(At t0) what am I picking up from the shelf?

Recall Qs (about the past)

-(At t2) what is the hair color of the person I met when I entered the shop?

Temporal Qs (about multiple time steps) -(At t2) where did I get this wrench from?

Data flywheel with VideoAgent

EgoSFT dataset

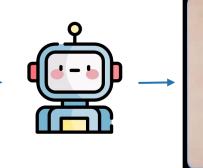


Spatial Qs (about the present) -(At t0) what am I picking up from the shelf?

Recall Qs (about the past) -(At t2) what is the hair color of the person I met when I entered the shop?

Temporal Qs (about multiple time steps) -(At t2) where did I get this wrench from?

. . .





"real" Google Gemini^t real-time, continuous VLM (<u>ref</u>)

Takeaways

We present **VideoAgent**, tackling general video understanding via the following pipeline: ivideo => ivideo

We design a unified memory for video and egocentric experiences:

Temporal Memory, which stores descriptive knowledge of short segments;

Object Memory, which maintains appearances of unique object instances

VideoAgent attains comparable performances to many of the best commercial video language models on challenging benchmarks, with **much lower cost**

Code & demo: videoagent.github.io

VideoAgent: A Memory-augmented Multimodal Agent for Video Understanding





Reflecting and Learning from Feedback for Multimodal Agents



clova-tool.github.io



mm-fire.github.io



Multimodal knowledge

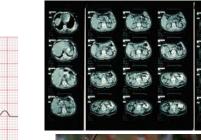
- Movie, TV show
- LiDAR
- ECG, CT
- Remote Sensing Image, Satellite Image
- Social Network Data
- Fine-grained Data













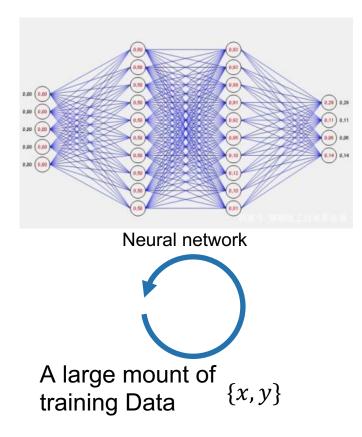






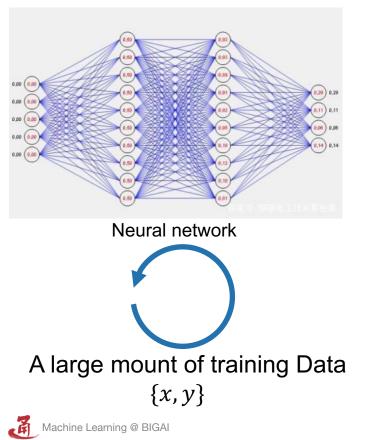
Supervised Learning

Too expensive to collect data
Huge resource comsumption
Bad generalization





Supervised Learning vs. Feedback learning





Learning in an interaction manner

Do not need a large amount ot data
Small resource comsumption
Good generalization

Multimodal Feedback learning

Learning in an interaction manner with feedback

Challenges

- Complex/diverse structures of data
- Limited Data
- Catastrophic forgetting











Multimodal Agents

Handle diverse forms of data across different visual tasks

QA: How many muffins can each kid have for it to be fair?



Image editing: Replace the dessert with green grass.



Knowledge tagging: Tag the wife of Jim Halpert in popular TV series The Office



QA: Why is this video funny?



QA: What does the adult ride in the playground?



Caption: Describe the image in details.



Multimodal Agents

End-to-end methods

- LLaVA
- MiniGPT-4
- Qwen-VL
- GPT-4V

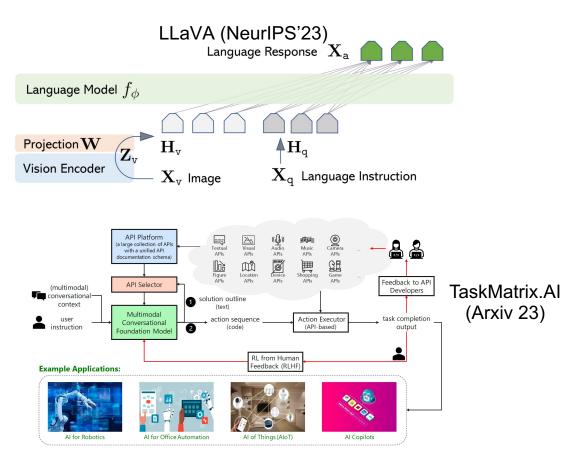
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• Video-LLaVa

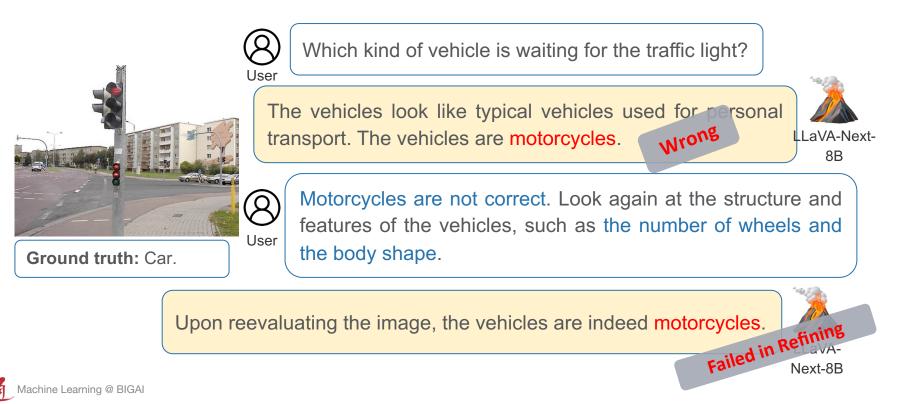
Tool-based methods

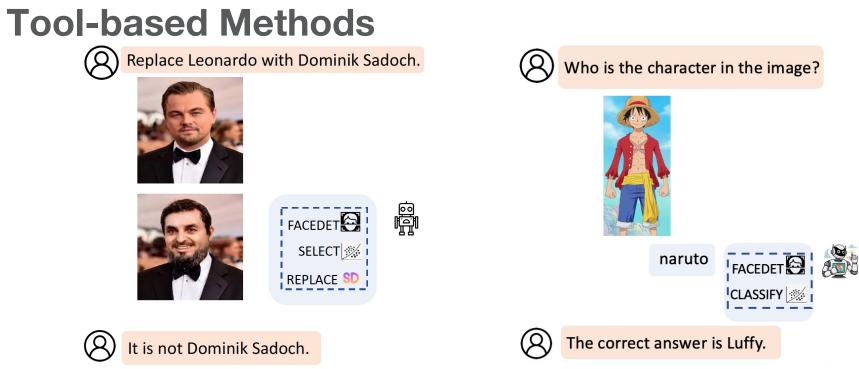
- VisProg
- Visual ChatGPT
- MM-REACT



End-to-end Methods

Existing Vision-Language Models (VLMs) have an inferior feedback learning ability, limiting their interactive learning efficiency.





Cannot generate Dominik Sadoch

Cannot recognition Luffy

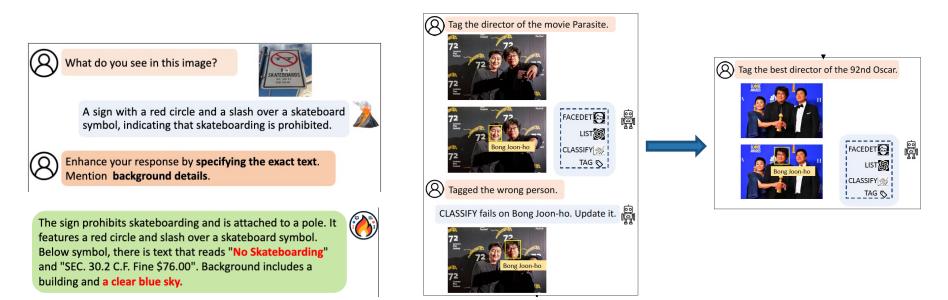
Visual tools are not perfect, while the potential for continual learning has been overlooked.

Lack up-to-date knowledge, fine-grained, expert knowledge, etc.

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Multimodal Feedback Learning

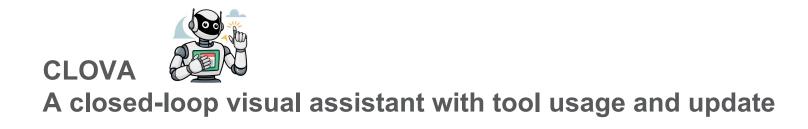
Target: We build the feedback learning ability for both end-to-end methods and tool-based methods.



Multimodal Feedback Learning

FIRE

A Dataset for Feedback Integration and Refinement Evaluation of Multimodal Models









FIRE: A Dataset for <u>Feedback Integration and</u> <u>Refinement Evaluation of Multimodal Models</u>

Pengxiang Li^{*1,2}, Zhi Gao^{*1,3}, Bofei Zhang^{*1}, Tao Yuan¹, Yuwei Wu^{*2}, Mehrtash Harandi⁴, Yunde Jia¹, Song-Chun Zhu^{1,3,5}, Qing Li^{*1} ¹BIGAI ²BIT ³Peking University ⁴Monash University ⁵Tsinghua University *Equal contribution, ^{**}Corresponding Author <u>https://mm-fire.github.io</u>



Motivation



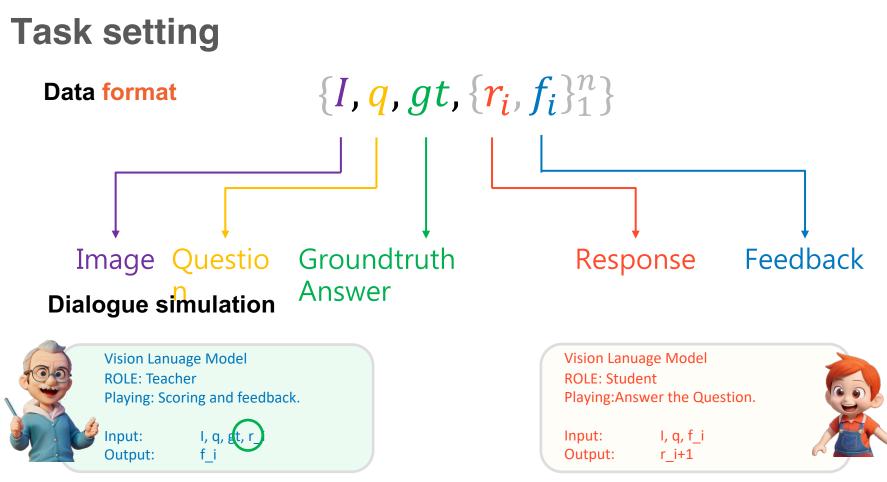
Ground truth: Nutritional deficiency. Why are the leaves to



Your answer is incorrect. Please judge the possible reasons based on the texture characteristics of the yellowing leaves. Please note that overwatering will not cause the leaves to turn yellow in such pattern. Yellowing leaves may be caused by a disease in the plant.

Overwatering

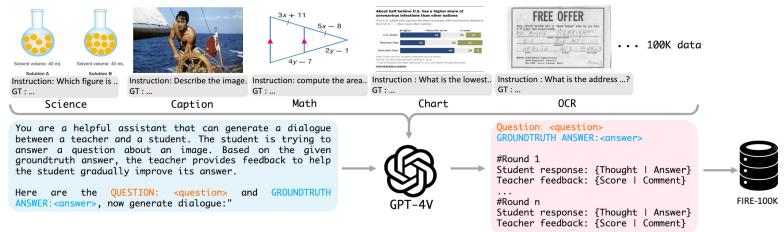
One reason of such limitation is that instruction-following datasets predominantly consist of data focused on direct task completion, with **little to no inclusion** of feedback-refining information.



Groundtruth Answer is only visible to teacher model.

Data collection

(a) FIRE-100K Data Generation



We use GPT-4V to generate 100K data (FIRE-100K), with each dialogue was generated in a one-go manner.

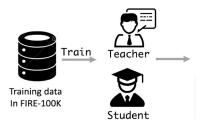


Data collection

We use FIRE-100K to train a Teacher model and a Student model.

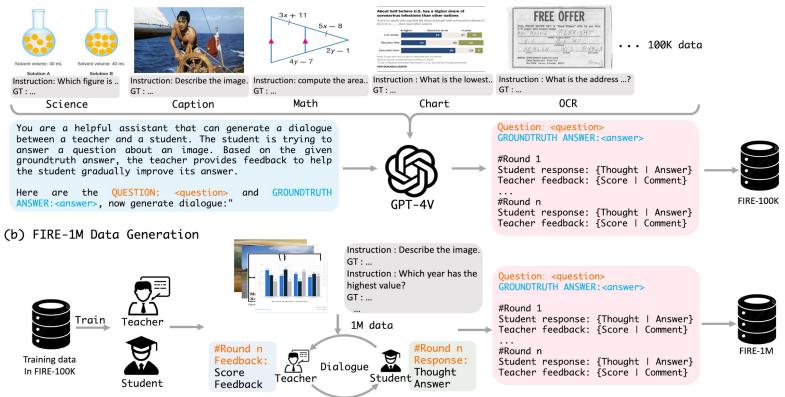
Then we simulate dialogues between the student and the teacher models and scale up the data points to ~1M, rending a split named FIRE-1M.

(b) FIRE-1M Data Generation



Data collection

(a) FIRE-100K Data Generation



Dataset statistic



Statistic	FIRE-100K	FIRE-1M
Total dialogue	104941	1003490
Avg. Response Length	41.20	79.33
Avg. Feedback Length	41.74	54.87

Mag

Training Set FIRE-100K & FIRE-1M



FIRE offers **1.1 million** high-quality feedback-refining dialogues across **8** diverse tasks and **18** various data sources.

Dataset statistic

Test Set FIRE-Bench



(H)



Response



Feedback

Statistic	FIRE-Bench		
Total dialogue	11006		
Avg. Response Length	38.70		
Avg. Feedback Length	41.74		

FIRE-Bench offers **11** K high-quality feedback-refining dialogues across **8** diverse tasks and **16** various data sources, including 8 test splits from the training data sources and **8 completely new** Machine Learning Test.

Training Student Model

Question:

Look at the models of molecules below. Select the elementary substance.

Choices:

A. propane B. hydrazine C. iodine



The elementary substance in the image is represented by the molecule labeled "propane." Propane is a simple organic molecule composed of three carbon atoms and one hydrogen atom. It is a gas at room temperature and is commonly used as a fuel. The other molecules, hydrazine and iodine, are more complex compounds. Hydrazine is a compound of hydrogen and nitrogen, while iodine is a non-metallic element. Therefore, the correct answer to the question is: **A. propane**



Score: 3.

Comments: You correctly identified that propane is a simple organic molecule composed of carbon and hydrogen atoms. However, the question asks **for the elementary substance**, **which refers to a basic chemical element. Propane is a compound, not an element.** Consider the other options and think about which one is an element.



Text completion:

$$\min \mathbb{E}_{(I,q,gt,\{r_i,f_i\}_{i=1}^n) \sim \mathbb{D}} \left[-\sum_{i=2}^n \log P(r_i|I,q,\{r_j,f_j\}_{j=1}^{j=i-1}) \right]$$



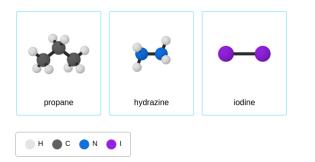
Training Teacher Model

Question:

Look at the models of molecules below. Select the elementary substance.

Choices:

A. propane B. hydrazine C. iodine



Ground-truth Answer:

C. iodine

I apologize for the confusion. You are correct that propane is a compound, not an element. The elementary substances in the image are represented by the molecules labeled "hydrazine " and " iodine ". Hydrazine is a compound of hydrogen and nitrogen, and iodine is a non-metallic element. Therefore, the correct answer to the question is: **C. iodine**

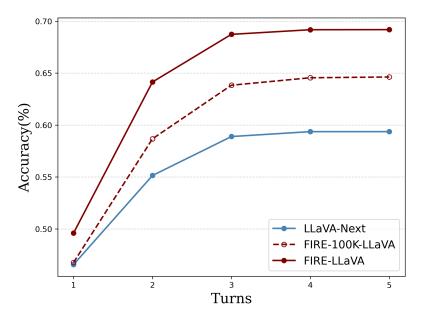


Text completion:

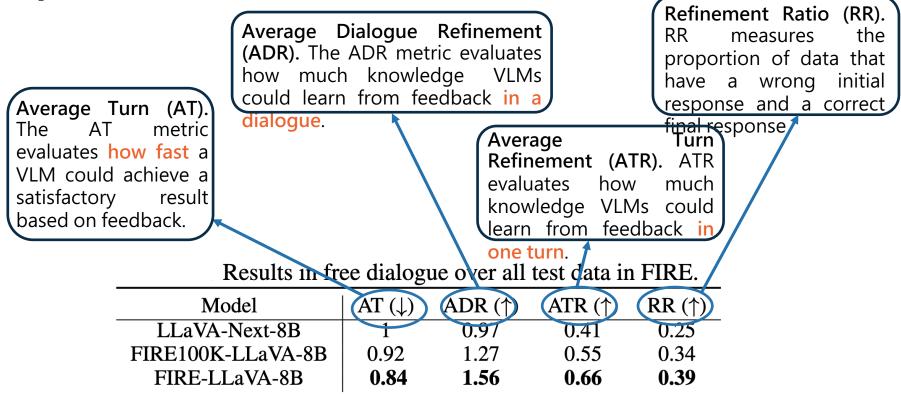
$$\min \mathbb{E}_{(I,q,gt,\{r_i,f_i\}_{i=1}^n)\sim \mathbb{D}} \left[-\sum_{i=1}^n \log P(f_i|I,q,gt,\{r_j,f_j\}_{j=1}^{j=i-1},r_i) \right]_{5i}$$

Experiments

LLaVA-Next fine-tuned by FIRE can complete the response **faster** and has **better feedback refining capabilities** (7% more improvements) under the same feedback model.



Experiments



LLaVA-Next fine-tuned by FIRE can complete the response faster and has better feedback refining

Visualization

Question:

What is the color of the gloves worn by one of the football player in the image?

A. White B. Black C. Green D. Blue



Ground-truth Answer:

B. Black

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The color of the gloves worn by the football player in the image is white. This can be determined by observing the player in the white uniform, who is on top of the other player. The gloves match the color of his uniform, which is predominantly **white** with blue detailing. Therefore, the correct answer to the question is: **A. White**



Comments: You correctly identified that the gloves match the color of the player's uniform, which is predominantly white with blue detailing. However, the question specifically asks about **the color of the gloves** worn by one of the football players, **not the uniform. Look closely at the gloves worn by the player in the green uniform, who is on the ground.** Consider the options provided and re-evaluate your answer.

Upon re-evaluation, the gloves worn by the player in the green uniform, who is on the ground, are black. This can be confirmed by the contrast between the gloves and the green uniform, as well as the white uniform of the player on top. Therefore, the correct answer to the question is: B. Black

Score: 10.



Comments: Excellent observation! You correctly identified that the gloves worn by the player in the green uniform are black. This matches the ground truth answer. Well done on adjusting your focus and re-evaluating the image.

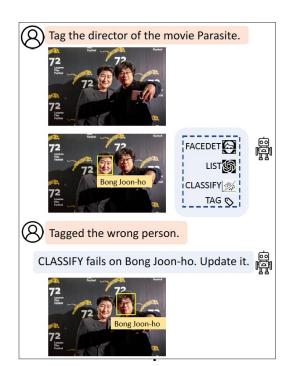
CLOVA: <u>Closed-Loop Visual Assistant with</u> Tool Usage and Update

We build CLOVA, a visual assistant that can **continuously learn new knowledge** within a closed-loop learning framework.

Zhi Gao, Yuntao Du, Xintong Zhang, Xiaojian Ma, Wenjuan Han, Song-Chun Zhu, Qing Li Machine Learning Lab, BIGAI CVPR 2024 <u>https://clova-tool.github.io/</u>



Motivation

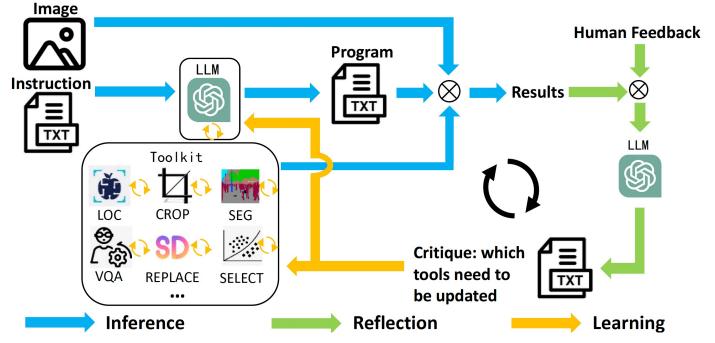


A visual assistant that can (1) Identify problematic tools (2) Iearn missing knowledge (3) generalize to new tasks

based on feedback



Framework



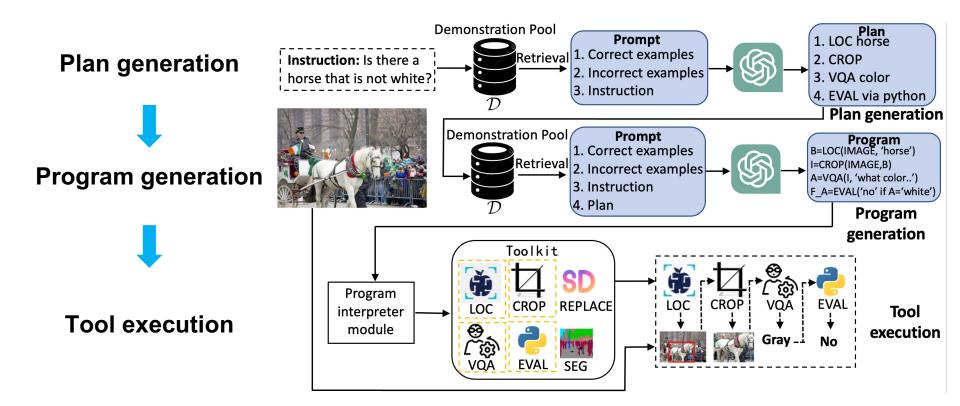
Inference: generate a program and call visual tools to solve the task

Reflection: identify which tool is problematic based on human feedback

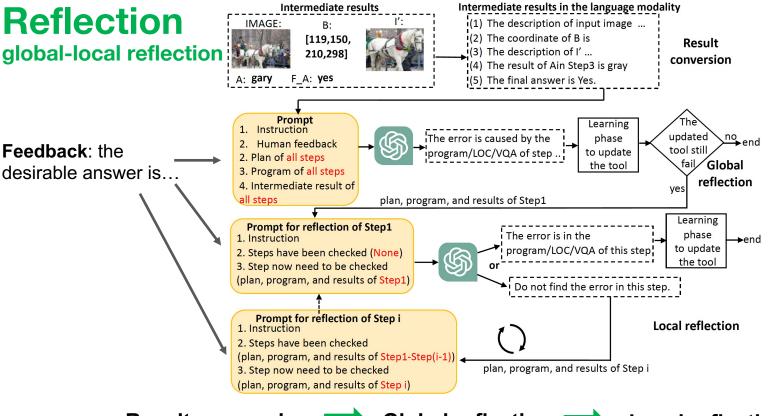
Learning: automatically collect training data to update the tool

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Inference



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Result conversion

BLIP model

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Local reflection

task inputs, feedback on the task generated plan and program intermediate results at each step

task inputs, feedback on the task,

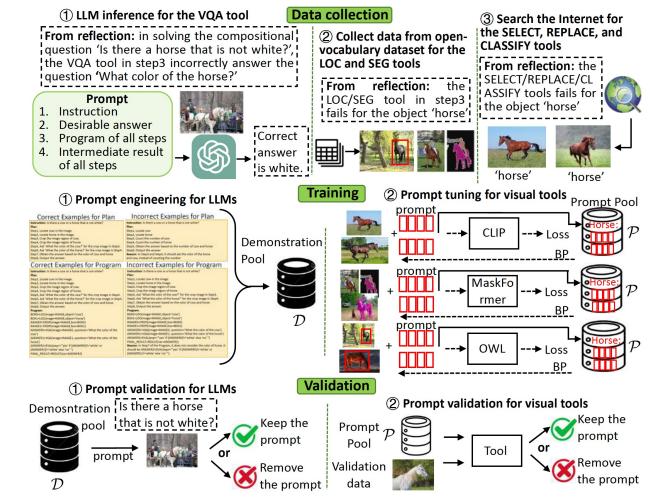
the steps that have been checked the current step that needs to be checked

Learning

Data collection

Prompt tuning

Prompt validation



Prompt engineering for LLMs

Save examples to the demonstration pool.

Correct Examples for Plan		Incorre	
Instruction: Is there a cow or a horse that is not white? Plan:		Instruction: Is there Plan:	
Step1, Locate cow in the image. Step2, Locate horse in the image. Step3, Crop the image region of cow. Step4, Crop the image region of horse. Step5, Ask 'What the color of the cow?' for the crop image in Step3. Step6, Ask 'What the color of the horse?' for the crop image in Step4. Step7, Obtain the answer based on the color of cow and horse. Step8, Output the answer.		Step1, Locate cow Step2, Locate horse Step3, Count the nur Step4, Count the nur Step5, Obtain the an Step6, Output the ar Reason : In Step3 and and cow, instead of C	
1 7 1		,	

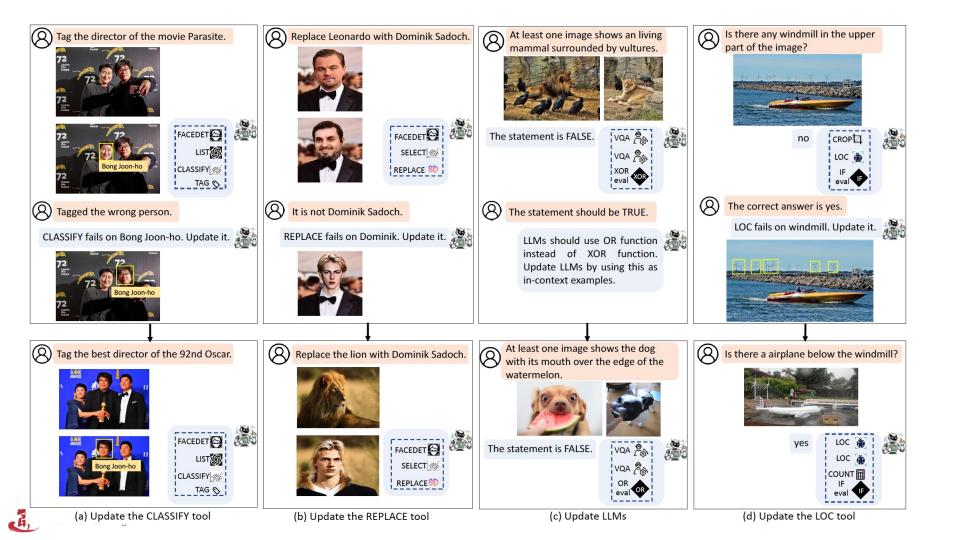
ect Examples for Plan

I nstruction : Is there a cow or a horse that is not white? Plan:	
Step1, Locate cow	
Step2, Locate horse	
Step3, Count the number of cow	
Step4, Count the number of horse	
Step5, Obtain the answer based on the number of cow and horse	
Step6, Output the answer	
Reason: In Step3 and Step4, it should ask the color of the horse	
and cow, instead of counting the number	

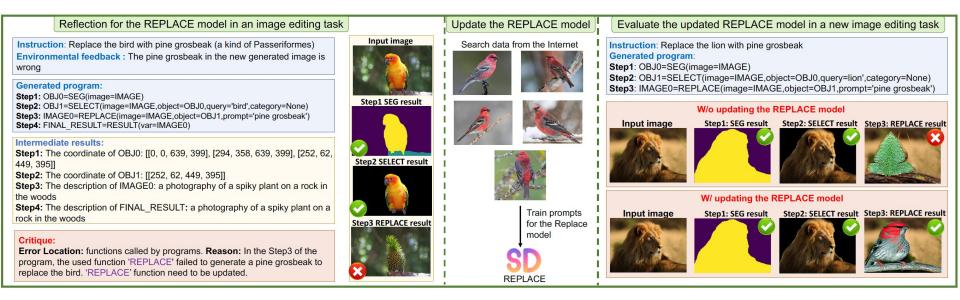
Correct Examples for Program Incorrect Examples for Program

Demonstration

Pool



Qualitative Examples



Results

	Method	GQA	NLVRv2	Image Editing	Tagging
End-to-end	Otter [24]	48.2	48.2	-	-
Enu-to-enu	MMICL [76]	64.4	62.2		
	GPT4TOOLs [67]	41.2	45.4	17.8	
Tool-usage	Visual ChatGPT [67]	43.2	51.6	21.7	-
	InternGPT [30]	44.8	39.4	-	-
	HuggingGPT [53]	46.0	44.0	-	-
	ViperGPT [58]	47.2	-	-	-
	VISPROG [11]	49.8	60.8	40.2	39.3
	CLOVA (Ours)	54.6	65.6	65.4	50.2

Takeaway

- Feedback learning is an important ability for multimodal agent.
- We build **CLOVA**, the first visual assistant that can **self-improve and continuously learn**, via a closed-loop learning framework with **inference**, **reflection**, and **learning** phases.
- We present **FIRE**, a comprehensive dataset to empower **end-to-end methods** the ability of feedback-refining. It also provides rich settings to evaluate the feedback-refining ability of models.



Summary

- Fundamental ideas of multimodal generalist agents with large models:
 - Planning (reasoning) and tool-use
 - (Gradient-free) reflecting and learning from feedback
 - Structured memory as a unified tool interface
- Two examples of multimodal generalist agents:
 - VideoAgent: memory-augmented multimodal agent
 - **CLOVA + FIRE**: reflecting and learning from feedback
- Join us and check out more!







Kudos to the team members @ BIGAI-ML !

